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INVERTER DRIVING DEVICE AND METHOD

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Cross Reference To Related Application

[0001] This application is based on Korea Patent Application No. 2002-48949 filed on August 19, 2002 in the Korean Intellectual Property Office, the content of which is incorporated herein by reference.

BACKGROUND OF THE INVENTION

(a) Field of the Invention

[0002] The present invention relates to an inverter driving device and method. More specifically, the present invention relates to an inverter driving device and method for frequency and duty control.

(b) Description of the Related Art

[0003] In general, a backlight used as a light source of an LCD uses a fluorescent lamp to configure a surface light source with uniform brightness. A CCFL (cold cathode fluorescent lamp) of a small size and enabling high-luminance light emission is generally used for the fluorescent lamp.

[0004] Conventional inverter drivers have a controller for controlling the current flowing to the CCFL so as to uniformly maintain the brightness of the backlight.

[0005] When an input voltage of the inverter driver or a load at the CCFL is varied, the current flowing to the CCFL is varied to change the brightness of the backlight.

Therefore, the conventional inverter drivers include a control signal supply for sensing the input voltage and a voltage corresponding to the current flowing to the CCFL to uniformly maintain the current flowing to the CCFL.

[0006] The conventional inverter driver uses an output voltage of the control signal supply to control the current flowing to the CCFL by using one of a duty control method and a frequency control method.

[0007] The inverter driver according to the conventional duty control method controls switching states of first and second switches coupled in series between the input voltage and the ground voltage to reduce the duty when the input voltage rises or the current flowing to the CCFL is high, and output a duty-increased pulse signal when the input voltage falls or the current flowing to the CCFL is low. A transformer converts the pulse signals to control the current flowing to the CCFL.

[0008] However, in the inverter driver according to the conventional duty control method, the current waveform of the CCFL is steeply varied when the duty greatly reduces or increases, and the brightness of the CCFL becomes unstable, interference occurs in the adjacent circuit because of many harmonics thereof, and the lifetime of the CCFL shortens.

[0009] The inverter driver according to the conventional frequency control method performs control by varying the operation frequency of the current at the CCFL. The inverter driver uses a variable resistor coupled to an oscillator to modify the current flowing to a capacitor coupled to the oscillator, thereby varying the operation frequency of the current of the CCFL.

[0010] In this instance, since the conventional inverter driver directly connects the current generated by comparing the reference voltage and the voltage at the load coupled to the CCFL to the variable resistor, it is difficult to control the variation range of the operation frequency. Also, when the CCFL dims, the maximum frequency may rise to 200KHz which causes an EMI problem, a switching loss problem, and a problem of digressing from the CCFL operation frequency range.

SUMMARY OF THE INVENTION

[0011] It is an advantage of the present invention to perform frequency control and duty control in parallel according to variation of the input voltage and the CCFL load.

[0012] In one aspect of the present invention, an inverter driver comprises:

[0013] an inverter circuit including a first switch and a second switch, for inverting DC components into AC components in response to a switching operation by the first and second switches to drive a load;

[0014] a control signal supply for outputting a first voltage corresponding to a voltage caused by sensing the current flowing to the load, and outputting a second voltage, and a third voltage generated by multiplying the first voltage by a predetermined gain;

[0015] a frequency controller including a capacitor and an oscillator having a first end coupled to the capacitor, for controlling a first current charged in/discharged from the capacitor through the first end of the oscillator in response to the first voltage, to control the frequency of the oscillator; and

[0016] a duty controller for comparing the third voltage and a fourth voltage charged in the capacitor, and controlling the duty of the first and second switches in response to comparison results.

[0017] In another aspect of the present invention, a driving method of an inverter driver comprising an inverter circuit including a first switch and a second switch, for inverting DC components into AC components in response to a switching operation by the first and second switches to drive a load; a control signal supply for outputting a first voltage corresponding to a voltage caused by sensing the current flowing to the load, and outputting a second voltage, and a third voltage generated by multiplying the first voltage by a predetermined gain; and a frequency controller including a capacitor and an oscillator having a first end coupled to the capacitor, comprises:

[0018] controlling a first current charged in/discharged from the capacitor through the first end of the oscillator in response to the first voltage to control the frequency of the oscillator; and

[0019] comparing the third voltage with a fourth voltage charged in the capacitor, and controlling the duty of the first and second switches in response to comparison results.

BRIEF DESCRIPTION OF THE DRAWINGS

[0020] The accompanying drawings, which are incorporated in and constitute a part

of the specification, illustrate an embodiment of the invention, and, together with the description, serve to explain the principles of the invention:

[0021] FIG. 1 shows an inverter driver according to a first preferred embodiment of the present invention;

[0022] FIG. 2 shows a ratio of a voltage V_1 versus a voltage V_2 , and a relation between a voltage V_{ct} and a frequency f in the inverter circuit 100;

[0023] FIG. 3 shows a signal waveform diagram according to a first preferred embodiment of the present invention; and

[0024] FIG. 4 shows a frequency controller in an inverter driver according to a second preferred embodiment of the present invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0025] In the following detailed description, only the preferred embodiment of the invention has been shown and described, simply by way of illustration of the best mode contemplated by the inventor(s) of carrying out the invention. As will be realized, the invention is capable of modification in various obvious respects, all without departing from the invention. Accordingly, the drawings and description are to be regarded as illustrative in nature, and not restrictive.

[0026] FIG. 1 shows an inverter driver according to a first preferred embodiment of the present invention.

[0027] The inverter driver comprises an inverter circuit 100, a control signal supply 200, a duty controller 300, and a frequency controller 400.

[0028] The inverter circuit 100 inverts the AC power input according to switching states of switches M1 and M2 to supply it to a CCFL 10 of an LCD backlight. The inverter circuit 100 comprises an inductor L1, primary capacitors C1 and C3, a transformer T1, and a secondary capacitor C2.

[0029] The inverter circuit 100 uses a serial/parallel resonance of a half bridge

inverter, and a resonance frequency of the inverter circuit 100 is a frequency whereby the total impedance of the inductor L1 and the capacitors C1, C2, and C3 becomes zero in the viewpoint of from the primary side to the secondary side of the inverter circuit 100.

[0030] Body diodes D1 and D2 are respectively coupled to the switches M1 and M2 of the inverter circuit 100, and the body diodes enable zero voltage switching of the switches M1 and M2 as described later.

[0031] The control signal supply 200 comprises resistors R1 and R2 coupled in series between the input voltage Vcc and ground; a subtractor 220 for subtracting a voltage Vnc at a node between the resistors R1 and R2 from a reference voltage Vr and outputting a subtraction voltage Va ($V_a = V_r - V_{nc}$); a comparator 240 for comparing a reference voltage Vref and a feedback voltage Vfb at a resistor Rsense sensing the current flowing to the CCFL 10, amplifying the comparison result, and outputting a voltage Vcomp; and a multiplier 260 for multiplying output signals of the subtractor 220 and the comparator 240 by a predetermined gain K to generate a voltage Vmo, and supplying the voltage Vmo to the duty controller 300.

[0032] Therefore, the output voltage Vmo of the control signal supply 200 is given as Equation 1.

Equation 1

$$V_{mo} = K \times V_{comp} \times (V_r - V_{nc})$$

[0033] The duty controller 300 comprises a comparator 310, an RS latch 320, an OR/NOR logic gate 330, a high-side gate driver 350, and a low-side gate driver 340.

[0034] The comparator 310 compares the output voltage Vmo of the control signal supply 200 with a voltage Vct charged in the capacitor Ct of the frequency controller 400, and provides a comparison result to the R end of the RS latch 320. The S end of the RS latch 320 receives clock signals CLK from an oscillator 410 of the frequency controller 400. Signals output from the Q' end of the RS latch 320 and the clock signals CLK of the oscillator 410 are input to two input ends of the OR/NOR logic gate 330. Two output signals of the OR/NOR logic gate 330 are respectively provided to the high-side gate driver 350 for driving the switch M1 and the low-side gate driver 340 for driving the

switch M2.

[0035] The frequency controller 400 comprises an oscillator 410, resistors R_t and R_f , a capacitor C_t , and a subtractor 420.

[0036] One end of the resistor R_t is coupled to the oscillator 410, and another end thereof is coupled to the ground voltage. In this instance, a voltage at a node of the oscillator 410 and the resistor R_t is uniformly V_{rt} volts, and the current I_{C2} flowing to the resistor R_t is V_{rt}/R_t .

[0037] One end of a resistor R_f is coupled to the node of the oscillator 410 and the resistor R_t , and another end thereof is coupled to the subtractor 420. The subtractor 420 subtracts the reference voltage V_x from the output voltage V_{comp} of the comparator 240 of the control signal supply 200. The subtractor 420 is realized by coupling a Zener diode having a voltage V_x or a diode (not illustrated) between the resistor R_f and the voltage V_{comp} in series.

[0038] When the voltage V_t obtained by subtracting the voltage V_x from the voltage V_{comp} is greater than the voltage V_{rt} , the current I_{C1} flows to the resistor R_f , and the current I_{Ct} which is the difference $I_{C2}-I_{C1}$ between the currents I_{C1} and I_{C2} flows to a terminal of the oscillator 410 to which the resistor R_t is coupled.

[0039] The capacitor C_t is coupled to the oscillator 410, and since the current flowing to the capacitor C_t is matched with the current I_{Ct} , the current I_{Ct} charges or discharges the voltage at the capacitor C_t .

[0040] In the first preferred embodiment of the present invention, the waveform of the voltage V_{ct} charged in the capacitor C_t is a sawtooth wave having a minimum voltage of 0.25V, and a maximum voltage of 1.75V.

[0041] Given an amplitude V of the voltage V_{ct} , the period of the voltage V_{ct} charged in the capacitor C_t is the summation of the charge time $(C_t V)/I_{Ct}$ and the discharge time $(C_t V)/I_{Ct}$, and accordingly, the frequency f of the voltage V_{ct} is given as Equation 2.

Equation 2

$$f = ICt / (2Ct \cdot V)$$

[0042] An operation of the inverter driver according to the first preferred embodiment of the present invention will now be described with reference to FIGs. 1, 2, and 3.

[0043] Referring to FIGs. 1 and 2, a frequency control operation will be described.

[0044] FIG. 2 shows a boosting ratio of a voltage V1 versus a voltage V2, and a relation between a voltage Vct and a frequency f in the inverter circuit 100.

[0045] The resonance frequency f_0 is a frequency when the total impedance of the inductor L1 and the capacitors C1 and C2 becomes zero.

[0046] The operation frequency region of the inverter driver is between the minimum frequency f_{low} and the maximum frequency f_{high} , and as given in Equation 2, since the capacitor Ct is constant and the amplitude V of the voltage Vct is also constant, the maximum frequency f_{high} is obtained when the current ICt is a maximum, and the minimum frequency f_{low} is obtained when the current ICt is a minimum.

[0047] Since $ICt = IC2 - IC1$ and $IC2 = V_{rt}/R_t$, the ICt becomes the maximum and the frequency of the voltage Vct accordingly becomes the maximum frequency f_{high} when $IC1 = 0$, and ICt becomes the minimum and the frequency of the voltage Vdt becomes the minimum frequency f_{low} when IC1 is the maximum.

[0048] In this instance, the minimum frequency f_{low} is set to be greater than the resonance frequency f_0 so that the inverter driver according to the first preferred embodiment may operate in the inductive load. That is, the phase of the current is set to be slower than the phase of the voltage.

[0049] When the phase of the current is slower than that of the voltage, the negative current starts to flow before the switch M1 is turned on in the inverter circuit 100, and accordingly, the current flows to the body diode D1. Therefore, since the voltage at both ends of the switch M1 becomes the same before the switch M1 is turned on, zero voltage switching is enabled when it is turned on.

[0050] In the like manner, since the positive current flows before the switch M2 is turned on, the current flows to the body diode D2, and the voltage at both ends of the

switch M2 becomes the same. Therefore, zero voltage switching is enabled when the switch is turned on.

[0051] As derived from FIG. 2, the basic concept of frequency control of the inverter driver according to the first preferred embodiment is to reduce the frequency f and increase the boosting ratio V_2/V_1 when the voltage V_{fb} at both ends of the resistor R_{sense} coupled to the CCFL 10 or the input voltage V_{cc} reduces, and to increase the frequency f and reduce the boosting ratio when the voltage V_{fb} or the input voltage V_{cc} increases, by using the fact that the boosting ratio is maximized when the frequency f of the voltage V_{ct} is the minimum frequency, and the boosting ratio is minimized when the frequency f of the voltage V_{ct} is the maximum frequency.

[0052] Therefore, as shown in FIG. 1, when the voltage V_t reduced by the amount of the voltage V_x from the voltage V_{comp} through a Zener diode or a diode is greater than the voltage V_{rt} , the current I_{C1} flows and the current I_{Ct} reduces, and the frequency f of the voltage V_{ct} accordingly reduces as given in Equation 2. Hence, the boosting ratio V_2/V_1 increases and the voltage V_{fb} rises.

[0053] When the voltage V_{fb} rises, the voltage V_{comp} falls, and the frequency f rises to sustain the voltage V_{comp} , thereby maintaining the brightness of the CCFL with no relation to variation of the input voltage V_{cc} to the CCFL 10.

[0054] When the frequency f reaches the maximum frequency f_{high} , the voltage V_x is set to make the voltage V_t match the voltage V_{rt} .

[0055] In this instance, when the subtractor 420 is realized using a Zener diode or a diode having the voltage V_x at both ends thereof, the voltage V_t does not become less than the voltage V_{rt} . Therefore, when the frequency f is equal to the maximum frequency f_{high} , no further current I_{C1} flows, and hence, the frequency f does not become greater than the maximum frequency f_{high} .

[0056] The reason for controlling the frequency to be under the maximum frequency f_{high} is that if the frequency reaches about 200KHz, it generates an EMI problem or a switching loss problem. Therefore, the inverter driver sets the frequencies in the suitable

range as the maximum frequency to prevent the frequency from exceeding the set limit.

[0057] The inverter driver prevents a further increase of the frequency when the frequency f of the voltage V_{ct} reaches the maximum frequency f_{high} , and varies the duty to maintain the voltage V_{fb} . That is, the inverter driver only performs frequency control between the minimum frequency f_{low} and the maximum frequency f_{high} , and stops the frequency control and performs duty control when the frequency f reaches the maximum frequency f_{high} .

[0058] A duty control operation will now be described referring to FIGs. 1 and 3.

[0059] FIG. 3 shows voltage variations of the R and S ends of the RS latch 320, the output end OUT1 of the high-side gate driver 350, and an output end OUT2 of the low-side gate driver 340 according to changes of the output voltage V_{mo} of the control signal supply 200.

[0060] As shown, the clock signals CLK of the oscillator are pulse signals having the same period as the voltage V_{ct} , and they are input to the S end of the RS latch.

[0061] Referring to FIG. 1, the voltage V_{mo} is input to an inverting end of the comparator 310, and the voltage V_{ct} charged in the capacitor C_t is input to a non-inverting end of the comparator 310, and when the voltage V_{mo} is greater than the voltage V_{ct} , an Off signal is input to the R end of the RS latch 320, and when the voltage V_{mo} is less than the voltage V_{ct} , an On signal is input to the R end of the RS latch 320.

[0062] As shown in FIG. 3, when Off signals are input to the R and S ends of the RS latch 320, the end OUT1 voltage becomes an On signal, and the end OUT2 voltage becomes an Off signal, and in the opposite case, the end OUT1 voltage becomes an Off signal, and the end OUT2 voltage becomes an On signal.

[0063] Therefore, when the input voltage V_{cc} increases, or the voltage V_{fb} increases because of load variation of the CCFL 10, the voltage V_{mo} reduces, and accordingly, the pulse width of the end OUT2 voltage reduces to t_2 from t_1 (i.e., the duty ratio reduces), and the voltage V_{fb} reduces. Hence, the brightness of the CCFL 10 becomes constant.

[0064] In this instance, the duty ratio is controlled to be under 50% for system

security.

[0065] As described above, since the duty ratio is not greater than 50% in the inverter driver according to the first preferred embodiment, the system becomes stable, and since the frequency of the output signal does not exceed a predetermined frequency range, no EMI problem or switching loss problem occurs.

[0066] An inverter driver according to a second preferred embodiment of the present invention will now be described referring to FIG. 4.

[0067] FIG. 4 shows a frequency controller in an inverter driver according to a second preferred embodiment of the present invention.

[0068] The inverter driver according to the second preferred embodiment is matched with that according to the first preferred embodiment except for a frequency controller.

[0069] The output voltage V_{comp} of the comparator 240 is input to a non-inverting end of the OP amp 430, and a resistor R_f is coupled between an inverting end of the OP amp 430 and the ground voltage. Since the voltages at the inverting and non-inverting ends of the OP amp 430 are the same, the voltage V_{comp} is applied to both ends of the resistor R_f , and the current $IC1$ flowing to the resistor R_f is V_{comp}/R_f .

[0070] A current mirror 440 including transistors $Q1$, $Q2$, and $Q3$ is coupled to the output end of the OP amp 430. Since no current is applied to the inverting end of the OP amp 430, the current flowing to the transistor $Q1$ is the same as the current $IC1$ flowing to the resistor R_f . Accordingly, the current $IC1$ flows to the transistor $Q3$ of the current mirror 440.

[0071] When the current mirror 440 is coupled to the resistor R_t , the current $IC1$ is applied to the resistor R_t . The resistor R_t is coupled to the current mirror 450 including a transistor $Q4$ having a base end coupled to the voltage V_{ref2} , and transistors $Q5$ and $Q6$. Since the voltage applied to the resistor R_t is a voltage $(V_{ref2}-V_{be})$ obtained by subtracting the voltage V_{be} between a base and an emitter from the voltage V_{ref2} applied to the base of the transistor $Q4$, the current $IC2$ flowing to the resistor R_t becomes $(V_{ref2}-V_{be})/R_t$.

[0072] Therefore, the current ICt flowing to the transistor Q4 is the same as the subtraction of the current IC1 from the current IC2, and accordingly, Equation 3 is given.

Equation 3

$$IC_t = (V_{ref2} - V_{be}) / R_t - V_{comp} / R_f$$

[0073] Therefore, the current mirror 450 supplies the current ICt to the oscillator 460.

[0074] The current ICt flows to the capacitor Ct coupled to the oscillator 460 to charge and discharge it, and the frequency f of the voltage at the capacitor is given in Equation 2.

[0075] As known from Equations 2 and 3, the frequency is the maximum when the voltage Vcomp is the greatest, and the frequency is the minimum when the voltage Vcomp is the least.

[0076] An operation of the inverter driver according to the second preferred embodiment of the present invention will be described.

[0077] The inverter driver performs duty control and frequency control.

[0078] When the input voltage Vcc increases, or when the voltage Vbe increases because of load variation of the CCFL 10 and the voltage Vcomp thus decreases, the current IC1 reduces and the current ICt increases in the frequency controller of FIG. 4, and hence, the frequency f of the voltage Vct increases. Therefore, as known from the relation between the frequency f and the boosting ratio V2/V1 of FIG. 2, the boosting ratio V2/V1 reduces, and the brightness of the CCFL 10 accordingly reduces.

[0079] Concurrently, the voltage Vcomp is input to the duty controller 300, and the duty reduces as shown in FIG. 3, and the brightness of the CCFL 10 reduces. The operation of duty control is described in the first preferred embodiment.

[0080] As described, since the inverter driver and method thereof concurrently processes the frequency control and duty control according to the input voltage and variation of the CCFL load, the duty is controlled within an appropriate range, the current waveform of the CCFL becomes stable, the harmonics reduce, and hence no interference

occurs in peripheral circuits, the maximum frequency reduces, and no EMI problem and switching loss problem are generated.

[0081] While this invention has been described in connection with what is presently considered to be the most practical and preferred embodiment, it is to be understood that the invention is not limited to the disclosed embodiments, but, on the contrary, is intended to cover various modifications and equivalent arrangements included within the spirit and scope of the appended claims.